

# DOING PHYSICS WITH A COMPUTER IN HIGH SCHOOLS: DESIGNING AND IMPLEMENTING NUMERICAL EXPERIMENTS

Maria Peressi and Giorgio Pastore

University of Trieste and CNR-INFM DEMOCRITOS



DEMOCRITOS  
DEmocritos MOdeling Center for  
Research In aTOMIC Simulation **INFM**

# Outline

- Introduction (simulations:  
role in physics and physics education)
- Our project in High Schools
- An example: the Brownian motion

# Introduction

Computers

**in physics research and in physics education:**

nowadays widely used for many purposes.

Here: **focus only on computer simulations**

= virtual experiments in which our representation of the physical reality, though necessarily

schematic and simplified, can be tuned and varied at

will (**“what-if” experiments**) => **Predictive power**

(“The purpose of computing is insight, not numbers”, R. Hamming)

# Computer simulations in physics research

The third paradigm of physics:

- experiment
- theory
- simulation

time for them to play a similar role  
in physics education?

# Computer simulations in physics education

- \* A specific aspect of computer aided physics teaching
- \* Already widely used as an interactive and efficient learning tool:
  - several powerful simulations software packages and integrated environments
  - many Java applets concerning physical phenomena
  - ...

BUT: students hardly can get a feeling of “what is a computer simulation” carrying on numerical experiments with a software ready-to-use

AN ALTERNATIVE APPROACH (not new, however...):

- going **beyond the use** of simulation software towards a **real computational physics laboratory**
- making students aware of “**what’s inside**” a simulation code
- **designing and implementing together with students** simple computer experiments to study real-world problems, the focus being on actual **problem solving**

A number of VALUABLE EXPERIENCES already done along these lines

# Our experience

with 16–18 years students with typical High School math/phys background

OUR CONTRIBUTION: Transfer of **tools and methodology** from **computational physics research** to **education**

FOCUS ON:

- problems that students can afford using **basic math. and phys. knowledge** normally available to them;
- problem solving; algorithms; select **basic numerical and graphical tools** (ours: “poor-man” simulations...)

NOT ON:

- specific programming languages or techniques
- sophisticated tools

# Our experience: organization of the project



- introductory lecture to classes



- assisted hands-on sessions in computer labs on specific problems (enrolled students; recently also at: “Summer School of Modern Physics for High School Students”, Udine, July 2009)

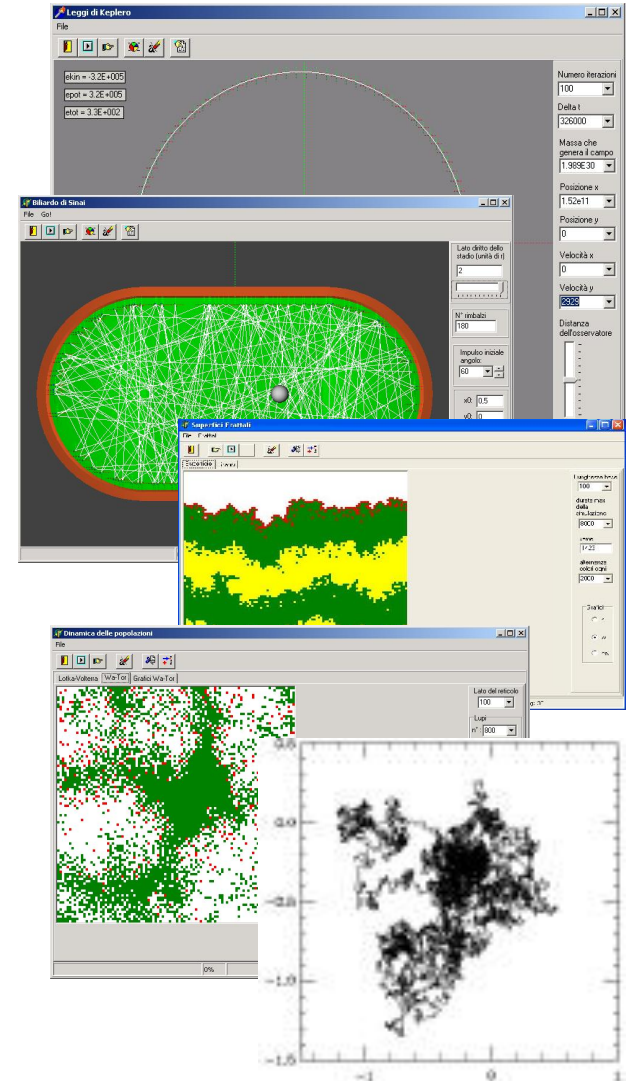


- on demand: additional sessions on programming language for motivated students



# Our experience: some specific problems

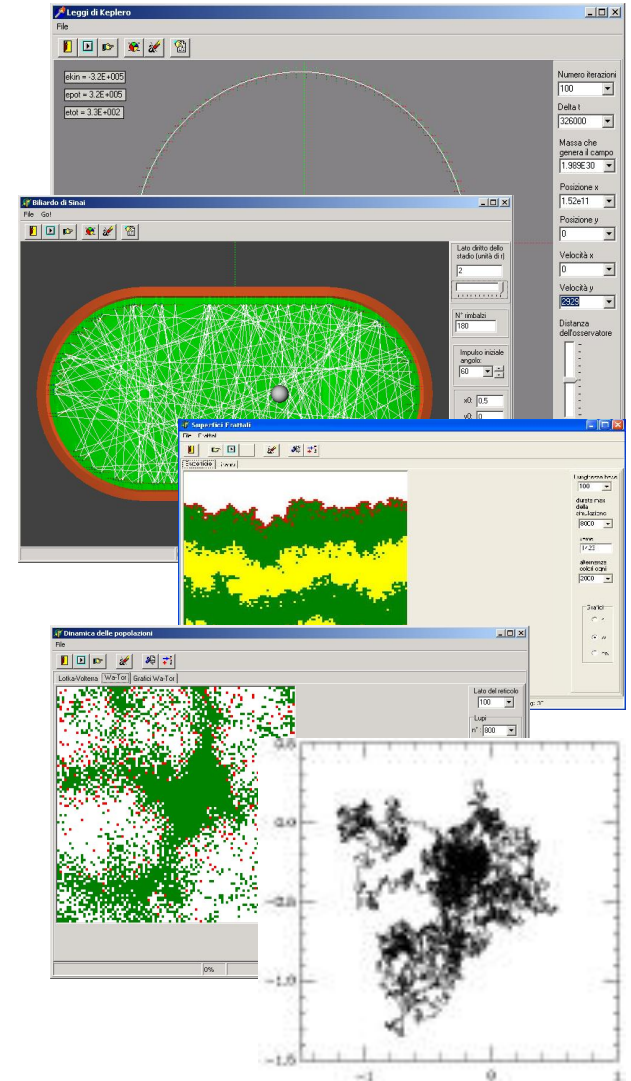
- motion of bodies in external forces  
(in gravitational fields [planets];  
in electrostatic and magnetic fields...)
- physics of classic billiards and chaos  
(from circular billiards to the stadium  
billiards)
- fractal growth of surfaces (different  
models)
- prey-predator problem
- ray optics (light refraction in  
inhomogeneous media)
- Brownian motion



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Brownian motion



# A case study: the Brownian motion

prototype of realistic problems

- **difficult to solve analytically** at high school level (requiring stochastic differential equations or integral calculus...)

but ...

- **easier to solve** numerically !

# The physical system

Einstein, 1905 – explanation of Brownian motion:

- The motion of pollen is due to a stochastic force<sup>(\*)</sup> caused by many collisions with solvent particles much smaller and light (not visible on the chosen observation scale).

<sup>(\*)</sup> can be dealt with statistical methods, without worrying about the details of the dynamics of the small molecules of the solvent

- measurable quantity: mean square displacement  $\langle R^2 \rangle$  of the particles

- key relation between diffusion coefficient  $D$  and solvent viscosity  $\eta$  (through a quite sophisticated mathematical treatment – not for students!) :

$$\langle R^2 \rangle = 2dDt \quad \text{with} \quad D = k_B T / (6\pi\eta P)$$

( $t$  time,  $d$  dimensionality of the system,  $P$  radius of brownian particles)

# The numerical approach: the ingredients

Here: NOT Einstein's, but Langevin's (1906) approach  
arriving at a Newtonian equation of motion including a  
*random force due to the solvent*

See: De Groot BG, Am. J. Phy. 67, 1248 (1999)

Ingredients:

- \* large Brownian particles – solvent interactions described by: **elastic collisions** between large particle (mass  $M$ , velocity  $V$ ) and small (solvent) particles ( $m$ ,  $v$ );
- \* **momentum and energy conservation** at each collision

$$MV + mv = MV' + mv'$$

$$MV^2/2 + mv^2/2 = MV'^2/2 + mv'^2/2$$

# The numerical approach: the equation of motion

After **reasonable assumptions** (*many collisions (i) in a time interval  $\Delta t$ , where  $V_i$  are the same...,  $m \ll M$ ..., ...*)  $\Rightarrow$

arrive at a simple expression for  $M\Delta V/\Delta t = M(V' - V)/\Delta t$  :

$$Ma = F_s - \gamma V(t)$$

$F_s$  : **stochastic force**, i.e. the cumulative effect, in the time interval, of many collisions with smaller particles

$-\gamma V(t)$  : **drag force**, opposite to  $V(t)$  ( $\gamma > 0$ );  $\gamma$  can be expressed (using Stokes' formula for a sphere of radius  $P$ ) as:  $\gamma = 6\pi\eta P$ .

(both forces have the same origin, in the collisions with the smaller particles)

# The numerical approach: discretization of the equation of motion

$$Ma = F_s - \gamma V(t)$$

Rewritten as:  $M\Delta V/\Delta t = \Delta V_s / \Delta t - \gamma V(t)$

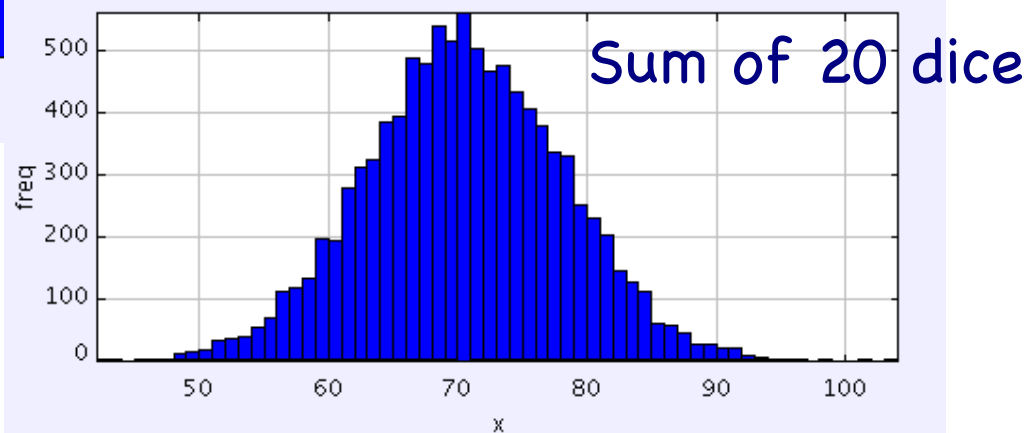
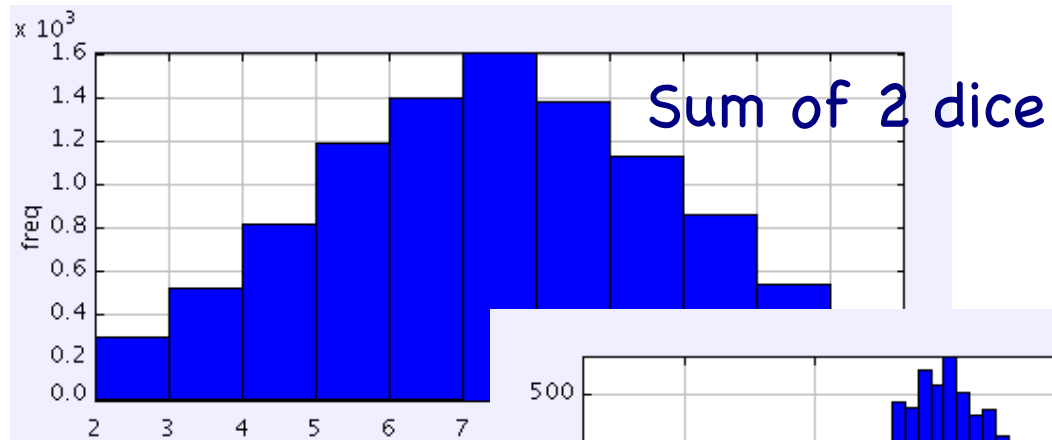
$$\Rightarrow V_{q+1} = V_q + \Delta V_s - \gamma(\Delta t/M)V_q$$

with:

$$\Delta V_s = 2mv/M = (\dots) = 1/M v/|v| \sqrt{(2\gamma k_B T/n)};$$

At each collision  $v/|v|$  is  $-1$  or  $+1 \Rightarrow$  after  $N$  collisions ???

Allowing students discover themselves (e.g. with dice-rolling experiments) that the result is a **gaussian random variable**  $w_q$  centered in 0, s.d.= $\sqrt{(N/2)}$   $\Rightarrow (\dots) \Rightarrow$





# The numerical approach:

## discretized equations for positions and velocities

$$V_{q+1} = V_q - (\gamma/M)V_q\Delta t + w_q(\sqrt{2\gamma k_B T \Delta t})/M$$

$$X_{q+1} = X_q + V_{q+1}\Delta t$$

- the heart of our numerical approach
- can be easily implemented for iterative execution

NOTE for students: we are NOT imposing any specific time dependence behavior: it will come out as an “**experimental**” result of the simulation

# The numerical approach:

## Input parameters - I

$$V_{q+1} = V_q [1 - (\gamma/M)\Delta t] + w_q(\sqrt{2\gamma k_B T \Delta t})/M$$

Discuss with students the parameters of the simulation:

- physical parameters of the system:  $T$  and  $\gamma$   
(through  $\eta$  and  $P$ :  $\gamma=6\pi\eta P$ )

# The numerical approach:

## Input parameters - II

$$V_{q+1} = V_q [1 - (\gamma/M)\Delta t] + w_q(\sqrt{(2\gamma k_B T \Delta t)})/M$$

- time step  $\Delta t$  : cannot be fixed a priori!

Some suggestions from physical and rough numerical considerations  
[( $\gamma/M$ ) $\Delta t$  < 1 to reproduce the situation of  $T \approx 0$  (damped motion)

$\Delta t$  too small: too long numerical simulations necessary...

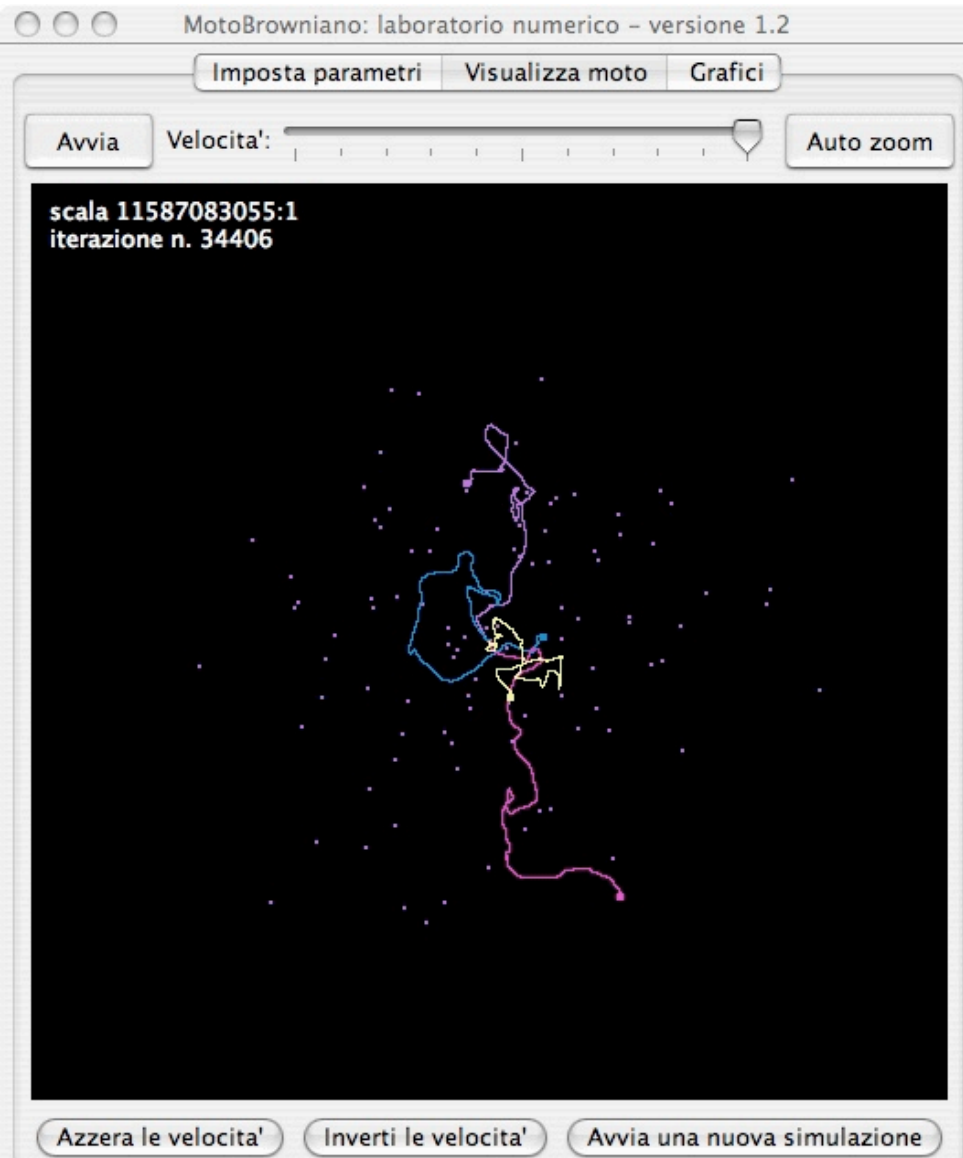
$\Delta t$  too large: serious numerical uncertainties...]

Encouraging students' work:

choice of  $\Delta t$  is analogous of an instrument calibration !!!

suggestion: start from small  $\Delta t$  s.t.  $\gamma \Delta t / M \ll 1$ , increase  $\Delta t$  until important changes in the diffusion coefficient are observed.

# Running the code...



$$k_B T = 4 \cdot 10^{-21} \text{ J}, \quad M = 1.4 \cdot 10^{-10} \text{ kg},$$

$$\gamma \approx 8 \cdot 10^{-7} \text{ N s/m}$$

*Snapshot of a numerical simulation  
of the Brownian motion in 2D  
of many large particles.*

*The trajectories of four of them are shown*

# Discovering the results

**Students can prove by numerical experiments:**

- (i) the linear behavior of the mean square displacement  $\langle R^2 \rangle$  with time:

$$\langle R^2 \rangle = 2dD \, t$$

- (i) the validity of the Einstein relation between the slope of this line and the solvent parameters (temperature and drag coefficient):

$$\langle R^2 \rangle = (2d \, k_B T / \gamma) \, t$$

# Open questions:

## which programming language?

A few considerations -

(i) the situation among teachers and among students:

- In Italian High Schools: information technology skills: very heterogeneous situation!
- In some classes: a limited know-how of rather “old” languages (Pascal in P.N.I. classes)
- Among teachers: some difficulties - no time, no funds, limited skills

(ii) Our wishes: easy, Open Source, possibly multi-platform

=> First experiences of our project: in Delphi/Pascal (free educational version) - Present experiences: Java

# The numerical approach: a possible implementation (Java)

...

```
double posPrec[]=new double[NDIM];
for (int ip=0;ip<nPart;ip++) {
    for (int jc=0;jc<NDIM;jc++) {
posPrec[jc]=pos[ip][jc];
vel[ip][jc] =
    vel[ip][jc] * ( 1 - gamma*dt/massa ) +
    random.nextGaussian()*Math.sqrt(gamma*kT*dt)/massa;
pos[ip][jc] += vel[ip][jc] * dt;
    }
```

# Conclusion

Simulation proposed to students of different High Schools.

Students: able to follow all steps of the analysis, including the implementation of the algorithm.

Two hands-on sessions (about three hours each one): a reasonable choice in order to introduce the physical problem and the specific algorithm, to become a bit familiar with random numbers and finally to understand and make individual numerical experiments with a provided working code.

Writing the code from scratch would be equally possible, but this would require previous training on computer programming.

**FOCUS on: problem solving, algorithms, calibration of the instrument, “experimental” approach**



A version of the Java software developed by the Authors  
and implementing the algorithm discussed here can be found in:  
<http://www.democritos.it/edu/>

General Web site of the educational projects in Physics of UniTS:  
<http://www.laureescientifiche.units.it/>  
(in Italian)



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*Thank you for your attention !*